

Patent Application of
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for

**TITLE: Hierarchical Method For Storing Data With Improved
Compression**

CROSS-REFERENCE TO RELATED APPLICATIONS

Not applicable

BACKGROUND--FIELD OF INVENTION

This invention relates to data storage, specifically to an improved data compression method.

BACKGROUND--DESCRIPTION OF PRIOR ART

Data compression gives data processing systems several performance advantages over non-compressed systems:

1. It allows larger data sets to be contained entirely in main memory. This allows faster processing than systems that must access the disk.
2. It allows a task to be performed while processing fewer bytes. This further speeds processing.

The nonleaf nodes ("interior nodes") (51) in Fig 2 represent tuples of tokens from lower (leaf or interior) nodes. Here, for simplicity, the

We look up token 1 in the root's left child (55) and get left and right values of 0 and 1. These are tokens for values in the City and First-Name dictionaries, respectively, which are "Plymouth" and "Bill", from the third record. A similar lookup with token 2 in interior node (52) gives "Smith" and "7" for the rest of the record.

For example, in node (56), the left/right pair for token 5 (4, 5) has each element one more than the left/right pair for token 4 (3, 4).

Exhaustively representing all the token pairs in a sequence with such a regular pattern wastes a considerable amount of space.

Also if other trees are constructed to represent subsets of the data in the first tree, the dictionary values used must be duplicated in the leaves of these other trees. This redundancy also wastes a considerable amount of space. It also wastes the processing time it takes to duplicate the dictionaries.

US patent 5,966,709 (1999) described a method of optimizing said tree structure. Said method used a variant of the Huffman Algorithm, which can produce sub-optimal tree designs when the value function is complex or nonmonotonic. Said method also calculates the exact size of a parent node by counting the tuples formed by the child nodes joined, which is computationally expensive.

US patents 5,023,610 (1991), 5,245,337 (1993), and 5,293,164 (1994) described the compression of a single stream of data, while this invention describes the compression of multiple parallel sequences of data.

In accordance with the present invention, an improved hierarchical data compression method uses:

- a) a more compact method for representing tuple sequences, which saves memory and time,
- b) data dictionaries shared among trees to avoid redundancy, which saves memory and time,
- c) an efficient method of processing a subset of a tree's leaves, and
- d) a flexible method of designing the tree.

Objects and Advantages

Accordingly, several objects and advantages of my invention are:

(a) to provide a more compact representation of data, by compressing an interior node's tuples, which saves space:

- (1) allowing larger data sets to be contained in main memory,
- (2) speeds the transfer of said interior node between secondary storage and main memory,
- (3) speeds the transfer of said interior node over a communication channel,
- (4) speeding up processing by allowing a task to be performed while processing fewer bytes, and
- (5) allowing data sets to be archived more efficiently;

(b) to provide a more compact representation of data by separating a tree's leaves from their corresponding dictionaries, which:

- (1) saves space when processing multiple trees which share the same dictionaries, by avoiding redundant copies of dictionaries
- (2) speeds the transfer of multiple trees between secondary storage and main memory, by only having to move one copy of each dictionary,
- (3) speeds the transfer of multiple trees over a communication channel,
- (4) saves space, allowing multiple trees to be archived more efficiently;

- ## DRAWING FIGURES

Fig 2 is prior art compression schemes

Fig 6 shows the nodes visited and avoided by gating

Fig 9 shows the algorithm for adding a tuple to an interior node that stores tuple runs separately

Fig 11 shows the tuples of Fig 10 represented with my method

Fig 13 shows the tuples of Fig 12 represented with my method

Fig 14 shows an algorithm for retrieving a subset of a token record

Fig 15 shows part of a problem space used in the design of a tree

Fig 16 shows the general algorithm used to search a problem space

50 leaf node, prior art

51 interior node, prior art

52 interior node over Last-Name and Shoe-Size leaves, prior art

53 the Last-Name dictionary, prior art

54 the Shoe-Size dictionary, prior art

55 interior node over City and First-Name leaves, prior art

56 the root node, prior art

57 token 2's entry in the root node, prior art

60 dictionaries, my method

61 leaves, my method

62 interior nodes, my method

63 the root node, my method

64 the single-tuple list in the root, my method

65 the tuple-run list in the root, my method

66 the City leaf node, my method

70 the initial state in the tree-design problem space

71, 72 two states in the problem space

80 the test whether a new pair extends the current tuple run

DESCRIPTION--Preferred Embodiment

1. Tree structure

Fig 3 shows an example of the storage method. The dictionaries (60) each associate the unique values of a field with a token number.

The tree leaves (61) are each associated with one dictionary, and represent a subset of that dictionary's values. In Fig 3, each leaf contains an array of counts, where the nth count is the number of times the nth dictionary value occurs in the input data sequence for that leaf.

Definition: *Run of unique, mutually-consecutive tuples.*

A sequence of tuples such that the elements of each tuple are each one more than the elements of the previous tuple, e.g.:

{(10, 20) (11, 21) (12, 22) (13, 23)}

Sub
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The tuple list (64) contains the single tuples corresponding to tokens 0, 1, and 11. The tuple run list (65) contains one run of nine tuples. The run list, in this case, takes one ninth as much space as explicitly representing the nine tuples.

Each leaf represents a subset of values from its corresponding dictionary. This can be done, for example, with an array of counts, such that the n th count is the number of times the n th dictionary value occurs in the leaves input data sequence.

A leaf's count array may contain many consecutive repetitions of the same count, and may be further compressed using run-length encoding.

3. Interior node gating

Each interior node has an integer, *gate*, associated with it. When access to only a subset of a tree's fields is needed for a record, we can speed up the process using the interior nodes' gates.

We store a value in each gate that tells if either of the interior node's subtrees contains a field in the subset we're interested in. This allows us to skip searching down subtrees that don't have any fields in the subset of fields we're looking for.

For example, see Fig 6. The shaded nodes are the ones we'd have to visit to retrieve values from nodes A, E, and F for a record. The number in each interior node in Fig 6 is the gate value to visit only leaf nodes A, E, and F.

A gate value of 0 means neither subtree contains a field in the subset. A value of 1 or 3 means the left subtree contains a field in the subset. A value of 2 or 3 means the right subtree contains a field in the subset.

Gating here visits 8 of 15 nodes, approximately halving the number of node visits required.

4. Tree construction process

A tree is constructed for a set of fields which have corresponding dictionaries. The design process is modeled as a search of a *problem space* with *operators* and a *value function*.

A problem space is:

(a) a set of *states* such that, each state represents a partial tree design; the leaves and zero or more interior nodes, each interior node the parent of two or more other nodes,

(b) one or more *operators* that transform one state to another, and

(c) a value function, giving a numeric ranking of the value of any state's design,

The design process starts from an initial state in the problem space, and applies operators to move to other states, until an acceptable design is reached.

Typical operators are: (a) joining multiple nodes under a new interior node, (b) a delete operation: deleting an interior node and separating its child nodes, (c) swapping two nodes.

Typical value functions may include the sizes of the interior nodes, preferences for certain fields to be near each other, and preferences that certain fields permit fast access.

For example, Fig 15 shows part of a problem space. The initial state (70) of the problem space contains three leaves: A, B, and C. The three states the initial state can reach in Fig 15 are each reached by applying the "Join" operator. This operator joins two nodes in a state, under an new interior node. In each of said three states, two of the leaves that were unjoined in the initial state are now joined.

We can transition from state (71) to state (72) in Fig 15, using the "Swap" operator. This operator exchanges the positions of two nodes, here, B and C.

Sub
A01 Applying the swap operator a second time undoes the swap operation, in effect, backtracking to the previous state in the problem space. The "Delete" operator deletes an interior node, which is the inverse of the join operator, so can backtrack from a join. Backtracking allows the problem space to be searched for an acceptable design.

DESCRIPTION--Alternative Embodiments

(a) Tuple run storage in interior nodes can be selectively enabled, storing only single tuples in the nodes where it has been disabled.

This avoids the overhead of two lists for lower interior nodes, where tuple runs are less frequent.

(b) Leaves can contain an array of Booleans, where the n th Boolean is TRUE if the n th dictionary value is present in a tree. This can be stored as a bit array, which is more compact than storing the counts, and can be further compressed by run-length encoding the bits.

(c) When designing a tree, the size of an interior node can be quickly approximated as a predetermined fraction of the product of said interior node's childrens' sizes. Although not optimal, this is much faster than the laborious calculation of the parent's exact size required by an optimal algorithm. A value of $1/3$ for said fraction produces reasonable results.

Operation

There are four basic operations on my invention:

1. Dictionary construction
2. Tree construction
3. Token record insertion
4. Access to a subset of a record

1. Dictionary construction

Fig 3 (60) is an example of four dictionaries, each of which associates a unique token number with each unique value that occurs in one field. Fig 7 shows the algorithm for adding a value to a dictionary. If the value is not already in the dictionary, it is added to the dictionary, and associated with the next unused token number.

2. Tree Construction

Tree construction is modeled as a search through a problem space. See Fig 15 for part of a problem space. Fig 16 shows the general algorithm

The process terminates when the current state represents an acceptable design. By varying the available operators and/or how they are selected, different problem-space search behaviors can be produced

When a record is added to a tree, each field value is first processed by a dictionary, mapping it to a token number. Thus the record is transformed into an equivalent record composed of tokens representing the original field values.

The interior node then, in turn, sends the token number associated with this pair to its parent. Thus, at each interior level, pairs (tuples) of tokens are recorded and mapped to single tokens. These pairs can later be looked up by their associated token number.

An interior node has a list of the left/right token pairs it has been sent from its left and right children. The interior node may optionally keep a list of pair (tuple) runs that have occurred. Fig 9 is a flow chart that shows how a pair is added to an interior node that stores tuple runs separately.

When a tuple is added to an interior node, there are four possible results:

(a) It can extend a tuple run .

(b) It can invalidate one or more existing runs by duplicating any of their tokens.

All left and all right values in a tuple run are assumed to occur only in that run. The tuple being added in Fig 11, (4, 4), duplicates a tuple in the run, thus invalidating that run. The run is then split into subruns that do not contain the tuples with duplicated values.

The form used inside the interior node is shown in Fig 13. The two entries on the left in Fig 13 represent the two runs in the node's tuple run list. The first run starts with token 0 and has a length of 3, and the second run starts with token 4 and has a length of 2. The entry on the right denotes token 3 is associated with left & right values of (4, 4), and has a count of 2.

(c) It may not do either 1 or 2, and is in the single-tuple list.

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(d) It may not do either 1 or 2, and the list.

In this case, we add the tuple to the single-tuple list with a count of one.

4. Access of Subset of a Record

To efficiently access a subset of a record, the gate fields of the interior nodes are set as previously described. We look at an example of accessing a record subset. The algorithm of Fig 14 is applied to a tree root to retrieve a token record for a given record number, and a subset of the fields.

See Fig 14. The input to the algorithm is:

- (a) the token number of the record to be retrieved,
- (b) a node to search from
- (c) the location to store the next token retrieved

The token number originally supplied to the algorithm is the record number. The node to search for is initially the root node over the subset of fields to be retrieved.

We look up left and right values from the given token number. If said node has a gate value of 1 or 3, we recursively search the node's left subtree, with said left value. If said node has a gate value of 2 or 3, we recursively search the node's right subtree, with said right value.

When a leaf is reached, we store the given token number at the next location in the token record we're constructing. We also increment the token-record location to point to the next space.

Thus the reader will see that my invention provides a more compact method of storing data records. This provides several benefits, including fitting larger data sets into main memory, allowing the data sets to be processed faster, improving the speed of loading/storing data between main memory and disk, and providing more efficient transmission and archival of said data sets.

An efficient algorithm for retrieving a record subset from this storage method is presented. A flexible algorithm for tree design is also presented.

While my above description contains many specificities, these should not be construed as limitations on the scope of the invention, but rather as an exemplification of one preferred embodiment thereof.

Accordingly, the scope of the invention should be determined not by the embodiment(s) illustrated, but by the appended claims and their legal equivalents.

Not applicable

Not applicable

[illegible]